

Communicative damper actuator for adjusting dampers in technical building installations

- $\bullet$  Air damper size up to approx. 1  $m^2$
- Torque motor 5 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Conversion of sensor signals
- Communication via Belimo MP-Bus

# Technical data



Electrical data	Nominal voltage	AC/DC 24 V
	Nominal voltage frequency	50/60 Hz
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V
	Power consumption in operation	2.5 W
	Power consumption in rest position	1.3 W
	Power consumption for wire sizing	5 VA
	Connection supply / control	Cable 1 m, 4 x 0.75 mm <sup>2</sup>
	Parallel operation	Yes (note the performance data)
Data bus communication	Communicative control	MP-Bus
	Number of nodes	MP-Bus max. 8
Functional data	Torque motor	5 Nm
	Torque variable	25%, 50%, 75% reduced
	Operating range Y	210 V
	Input Impedance	100 kΩ
	Operating range Y variable	Start point 0.530 V
		End point 2.532 V
	Options positioning signal	Open/close
		3-point (AC only)
	Desition foodback U	Modulating (DC 032 V)
	Position feedback U	210 V
	Position feedback U note	Max. 0.5 mA
	Position feedback U variable	Start point 0.58 V End point 2.510 V
	Position accuracy	±5%
	Direction of motion motor	selectable with switch 0/1
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) /
	Direction of motion note	1 (cw rotation)
	Direction of motion variable	electronically reversible
	Manual override	with push-button, can be locked
	Angle of rotation	Max. 95°
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops
	Running time motor	150 s / 90°
	Running time motor variable	35150 s
	Adaptation setting range	manual
	Adaptation setting range variable	No action
		Adaptation when switched on
		Adaptation after pushing the gear
		disengagement button

# Technical data sheet

LM24A-MP

MP27BUS



Functional data	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0%
	Override control variable	ZS (intermediate position, AC only) = 50% MAX = (MIN + 32%)100% MIN = 0%(MAX – 32%) ZS = MINMAX
	Sound power level, motor	35 dB(A)
	Mechanical interface	Universal shaft clamp 620 mm
	Position indication	Mechanically, pluggable
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)
	Power source UL	Class 2 Supply
	Degree of protection IEC/EN	IP54
	Degree of protection NEMA/UL	NEMA 2
	Enclosure	UL Enclosure Type 2
	EMC	CE according to 2014/30/EU
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14
	Certification UL	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1 The UL marking on the actuator depends on the production site, the device is UL-compliant in any case
	Mode of operation	Туре 1
	Rated impulse voltage supply / control	0.8 kV
	Pollution degree	3
	Ambient temperature	-3050°C
	Storage temperature	-4080°C
	Ambient humidity	Max. 95% RH, non-condensing
	Servicing	maintenance-free
Weight	Weight	0.50 kg

### Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.



Mode of operation	Conventional operation:
	The actuator is connected with a standard modulating signal of 010 V and drives to the position defined by the control signal. The measuring voltage U serves for the electrical display of the actuator position 0.5100% and as control signal for other actuators.
	Operation on Bus:
	The actuator receives its digital positioning signal from the higher level controller via the MP- Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti- rotation device to prevent the actuator from rotating.
Manual override	Manual override with push-button possible (the gear is disengaged for as long as the button is pressed or remains locked).
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).
	The actuator then moves into the position defined by the positioning signal.
	$(\mathbf{V}_{1})^{0} = 0 \mathbf{V}  \mathbf{ccw} \mathbf{V}$
Adaptation and synchronisation	An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC- Tool. Both mechanical end stops are detected during the adaptation (entire setting range).
	Automatic synchronisation after pressing the gearbox disengagement button is configured. The synchronisation is in the home position (0%).
	The actuator then moves into the position defined by the positioning signal.
	A range of settings can be adapted using the PC-Tool (see MFT-P documentation)
es	

# Accessories

Gateways	Description	Туре
	Gateway MP zu BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD



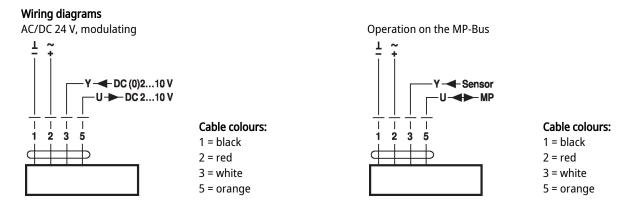
LM24A-MP

Electrical accessories	Description	Туре
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Feedback potentiometer 140 $\Omega$ add-on	P140A
	Feedback potentiometer 200 $\Omega$ add-on	P200A
	Feedback potentiometer 500 $\Omega$ add-on	P500A
	Feedback potentiometer 1 k $\Omega$ add-on	P1000A
	Feedback potentiometer 2.8 k $\Omega$ add-on	P2800A
	Feedback potentiometer 5 k $\Omega$ add-on	P5000A
	Feedback potentiometer 10 k $\Omega$ add-on	P10000A
	Signal converter voltage/current 100 kΩ Supply AC/DC 24 V	Z-UIC
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	MP-Bus power supply for MP actuators	ZN230-24MP
Mechanical accessories	Description	Туре
	Shaft extension 170 mm Ø10 mm for damper shaft Ø 616 mm	AV6-20
	Shaft clamp one-sided, clamping range Ø620 mm, Multipack 20 pcs.	K-ELA
	Shaft clamp one-sided, clamping range Ø610 mm, Multipack 20 pcs.	K-ELA10
	Shaft clamp one-sided, clamping range Ø613 mm, Multipack 20 pcs.	K-ELA13
	Shaft clamp one-sided, clamping range Ø616 mm, Multipack 20 pcs.	K-ELA16
	Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180
	Form fit insert 8x8 mm, Multipack 20 pcs.	ZF8-LMA
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-LMA
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-LMA
	Form fit insert 8x8 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL8-LMA
	Form fit insert 10x10 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL10-LMA
	Form fit insert 12x12 mm, with angle of rotation limiter and position indication, Multipack 20 pcs.	ZFRL12-LMA
	Position indicator, Multipack 20 pcs.	Z-PI
Service tools	Description	Туре
	Service Tool, with ZIP-USB function, for parametrisable and communicative Belimo actuators, VAV controller and HVAC performance devices	ZTH EU
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to service socket	ZK1-GEN
	Connection cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection to MP/PP terminal	ZK2-GEN

### **Electrical installation**

Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.





A) additional MP-Bus nodes

Switching current 16 mA @ 24

range must be parametrised on

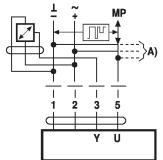
• Start point of the operating

the MP actuator as  $\geq 0.5 \text{ V}$ 

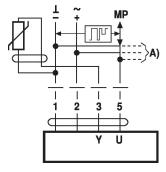
(max. 8)

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#### Connection of active sensors



Connection of passive sensors



A) additional MP-Bus nodes

• Output signal DC 0...10 V

• Supply AC/DC 24 V

(max. DC 0...32 V)

Resolution 30 mV

(max. 8)

Ni1000	–28+98°C	8501600 Ω <sup>2)</sup>
PT1000	–35+155°C	8501600 Ω <sup>2)</sup>
NTC	-10+160°C <sup>1)</sup>	200 Ω60 kΩ <sup>2)</sup>

A) additional MP-Bus nodes (max. 8) 1) Depending on the type 2) Resolution 1 Ohm Compensation of the measured value is recommended

Connection of external switching contact

MP

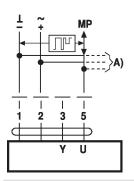
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### **Functions**

Functions when operated on MP-Bus Connection on the MP-Bus

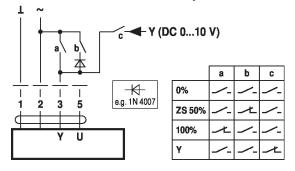




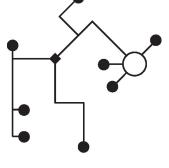
A) additional MP-Bus nodes

(max. 8)

Functions with basic values (conventional mode) Override control with AC 24 V with relay contacts



MP-Bus Network topology

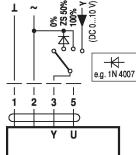


There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in

one and the same 3-wire cable no shielding or twisting necessary

• no terminating resistors required

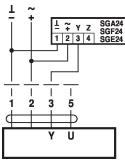
Override control with AC 24 V with rotary switch

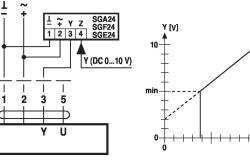




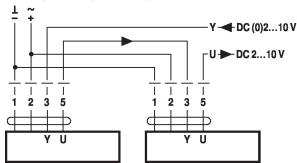
Minimum limit with positioner SG..

Control remotely 0...100% with positioner SG..

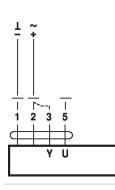




Follow-up control (position-dependent)



#### **Functional check**

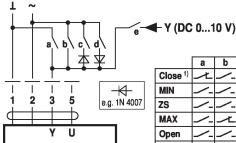


### Procedure

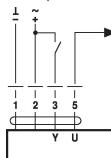
1. Connect 24 V to connections 1 and 2 2. Disconnect connection 3: - with direction of rotation 0: Actuator rotates to the left - with direction of rotation 1: Actuator rotates to the right 3. Short-circuit connections 2 and 3: - Actuator runs in opposite direction

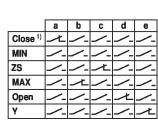
Functions with specific parameters (parametrisation necessary) Override control and limiting with AC 24 V with relay contacts

U

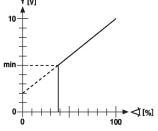


Control open/close

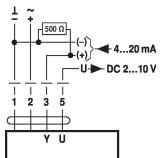




**Control 3-point** L - U e.g. 1N 4007 Г b I I Ì. I а 2 3 1 5 d b U セ 4



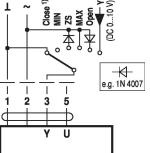
Control with 4...20 mA via external resistor



### Caution:

The operating range must be set to DC 2...10 V. The 500  $\Omega$  resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V

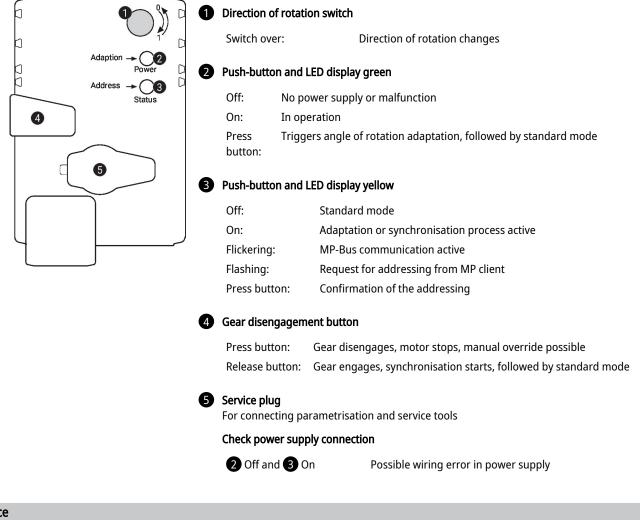
Override control and limiting with AC 24 V with rotary switch



1) Caution: This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.



### Operating controls and indicators

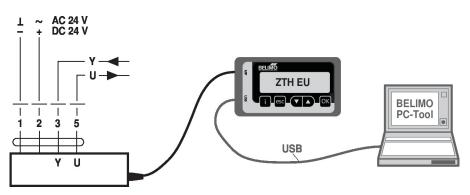


Service

Service tools connection

The actuator can be parametrised by ZTH EU via the service socket.
For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool





# Spindle length

Clamping range

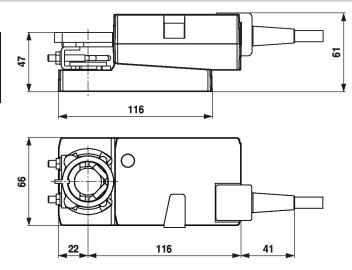
6...20



≥6

 $\mathbf{A}$ 

≤20



# Further documentation

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology

# Application notes

• For digital control of actuators in VAV applications patent EP 3163399 must be considered.